

Lizheng Deng, Hongyong Yuan, & Lida Huang. (2018). Optimal UAV 3D Path Planning in Mountainous Environments for Post-Earthquake Multi-region Search. In Kees Boersma, & Brian Tomaszewski (Eds.), *ISCRAM 2018 Conference Proceedings - 15th International Conference on Information Systems for Crisis Response and Management* (p. 1122). Rochester, NY (USA): Rochester Institute of Technology.